Assign actions to robots

Robot motions & programming · https://convergent-it.com/it/tutorial/robot-motions-programming-it/assign-actions-to-robots-it/

The video describes (in 2 different examples with 1 and 2 robots and external axes) how to assign one or several tool paths (including meanders etc.), which has been created in the setup, to a robot in a workflow. This specifies (initally) which robots are executing which tool-paths at which time. Assignment, order and timing can be changed later easily.

The video is embedded by YouTube and only loaded and played from there when you click on the play button. From then on, the privacy policy of Google applies.